

Matrix method of polynomial solutions to constant coefficient PDE's

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12 января 2022 г.

- The problem to find a polynomial solution to constant coefficient PDE('s) is a familiar problem, see for example [1–6]. And the well-known methods to find polynomial solutions are based on (complicated) general algebra approaches (like the using of the Macaulay matrices, primary decompositions of ideals, and so on).
- ① Abramov S., Petkovšek M. On polynomial solutions of linear partial differential and (q -)difference equations. In: Computer Algebra in Scientific Computing. 14th International workshop LNCS 7442, 1–11 (2012)
- ② Horvás J. Basic sets of polynomial solutions for partial differential equations. Proc. Amer. Math. Soc. 9, 569–575 (1958)
- ③ Karachik V.V. Polynomial solutions to the systems of partial differential equations with constant coefficients. Yokohama Math. J. 2000. N. 47. P. 121–142.
- ④ Pedersen P. A basis for polynomial solutions to systems of linear constant coefficient PDE's. Adv. Math. 117, 157–163 (1996)
- ⑤ Reznick B. Homogeneous polynomial solutions to constant coefficient PDE's. Adv. Math. 117, 179–192 (1996)
- ⑥ Smith S.P. Polynomial solutions to constant coefficient differential equations. Trans. Amer. Math. Soc. 329, 551–569 (1992)

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- **On the other hand, the finding of a polynomial that the polynomial is solution to constant coefficient PDE('s) can be, equaling the same degree terms, easily reduced to solving to a linear algebraic system.**
- So, the linear algebra approach to find a polynomial solution to constant coefficient PDE('s) is elementary and, probably, more effective.
- In this report, see also [7], we present a constructive method to obtain the matrix of the linear algebraic system.
- Further, our matrix approach allows to investigate in more detail some linear algebra properties of the polynomial space, for example, dimension, basis, affine invariance etc.
- Moreover, our method allows to use elementary computer code (in Mathematica, for example) to obtain a polynomial basis for any constant coefficient PDE('s).

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- d -tuple $\alpha = (\alpha_1, \dots, \alpha_d) \in \mathbb{Z}_{\geq 0}^d$ is **multi-index**;
- $|\alpha| := \alpha_1 + \dots + \alpha_d$ **length** of a multi-index $\alpha = (\alpha_1, \dots, \alpha_d)$;
- for $\alpha, \beta \in \mathbb{Z}_{\geq 0}^d$, we write $\beta \leq \alpha$ if $\beta_j \leq \alpha_j$ for all $j = 1, \dots, d$;
- $\alpha! := \alpha_1! \cdots \alpha_d!$;
- **binomial coefficient** for multi-indices α, β are:
$$\binom{\alpha}{\beta} := \binom{\alpha_1}{\beta_1} \cdots \binom{\alpha_d}{\beta_d} = \frac{\alpha!}{\beta!(\alpha-\beta)!}, \quad \binom{\alpha}{\beta} = 0 \quad \text{if } \beta \not\leq \alpha;$$
- **monomial**: $x^\alpha := x_1^{\alpha_1} \cdots x_d^{\alpha_d}$, $x := (x_1, \dots, x_d)$, $\alpha := (\alpha_1, \dots, \alpha_d) \in \mathbb{Z}_{\geq 0}^d$;
- $l \in \mathbb{Z}_{\geq 0}$, **polynomial spaces** are:
 - $\Pi_l := \text{span} \{x^\alpha : \alpha \in \mathbb{Z}_{\geq 0}^d, |\alpha| = l\}$ total degrees of polynomials are equal to l ;
 - $\Pi_{\leq l} := \text{span} \{x^\alpha : \alpha \in \mathbb{Z}_{\geq 0}^d, |\alpha| \leq l\}$ total degrees of polynomials are less than or equal to l ;
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Remark

- Since the linear algebra definitions and assertions are valid for any field; we can consider polynomials with coefficients from an arbitrary field.
- On the other hand, considering d -variate polynomials in the space \mathbb{C}^d , we have all zeroes of the multivariate polynomials.

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Definition

$f, g \in L^2(\mathbb{C}^d)$, an inner product in the space $L^2(\mathbb{C}^d)$ is:

$$\langle f, g \rangle := \int_{\mathbb{C}^d} f(x) \overline{g(x)} dx. \quad (*)$$

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- 1 И.М. Гельфанд, Г.Е. Шилев. Обобщенные функции и действия над ними. М.: Добросвет, 2000.
 - 2 А.Н. Колмогоров, С.В. Фомин. Элементы теории функций и функционального анализа. М.: Наука, 2004.
- S' space of tempered distributions;
 - S Schwartz space (of test functions);

Definition ([1,2])

Let $\phi \in \mathcal{S}(\mathbb{C}^d)$ be a complex test function. Let $f = f(x)$, $x \in \mathbb{C}^d$, be a locally integrable on \mathbb{C}^d complex function. Then the function f induces some distribution (continuous linear functional) on $\mathcal{S}(\mathbb{C}^d)$ as follows

$$\int_{\mathbb{C}^d} \overline{f(x)} \phi(x) dx = \langle f, \phi \rangle, \quad (**)$$

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- **I identity operator;**
- $\delta_{jk} := \begin{cases} 1, & j = k, \\ 0, & j \neq k; \end{cases} \quad j, k \in \mathbb{Z}_{\geq 0},$ **Kronecker delta;**
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if $x, y \in \mathbb{C}^d$, then $x \cdot y$ defined by (*) is, in fact, a semi-dot product: $y \cdot x \neq \overline{x \cdot y}$;

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- $l \in \mathbb{Z}_{\geq 0}, x_0 \in \mathbb{C}^d, x = (x_1, \dots, x_d)$:

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- $\mathfrak{F} : \mathbb{C}^d \rightarrow \hat{\mathbb{C}}^d$ Fourier transform:

$$f(x) \mapsto \hat{f}(\xi) = (\mathfrak{F}f)(\xi) := (2\pi)^{-d/2} \int_{\mathbb{C}^d} f(x) e^{-i\xi \cdot x} dx, \quad x \in \mathbb{C}^d, \xi \in \hat{\mathbb{C}}^d;$$

- multidimensional Leibniz rule is:

$$(fg)^{(\alpha)} = \sum_{\substack{\beta \in \mathbb{Z}_{\geq 0}^d \\ \beta \leq \alpha}} \binom{\alpha}{\beta} f^{(\beta)} g^{(\alpha-\beta)}, \quad \alpha \in \mathbb{Z}_{\geq 0}^d.$$

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however we shall use **(**)** only in a specially noted space with the Cartesian coordinate system;

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- $x_0 \in \mathbb{C}^d, \alpha \in \mathbb{Z}_{\geq 0}^d$: $\left(\mathfrak{F} e^{ix_0 \cdot x} x^\alpha \right) (\xi) = i^{|\alpha|} D^\alpha \delta(\xi - x_0).$

- $P(-iD)$ the differential operator *induced* by the polynomial $P \in \Pi$;

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- $$\left(\mathfrak{F} P(-iD) \right) (\xi) = P(\xi).$$

Remark

Below, abusing notations, for a function $f = f(x)$ and constant point x_0 , we shall write everywhere $D^\alpha f(x_0)$, meaning, in fact, $D^\alpha f(x)|_{x=x_0}$.

- $<_{\text{lex}}$ a *lexicographical order*;
- \mathcal{A}_k , $k \in \mathbb{Z}_{\geq 0}$, *lexicographically ordered set* of all multi-indices of length k :

$$\mathcal{A}_k := \left({}^1\alpha, {}^2\alpha, \dots, {}^{d(k)}\alpha \right), \quad \begin{array}{l} {}^q\alpha \in \mathbb{Z}_{\geq 0}^d, \quad |{}^q\alpha| = k, \quad q = 1, \dots, d(k), \\ {}^q\alpha <_{\text{lex}} {}^{q'}\alpha \iff q < q'; \end{array}$$

- $d(k)$ *number of k -combinations with repetition from the d elements*:

$$d(k) := \binom{d+k-1}{k} = \frac{(d+k-1)!}{k!(d-1)!};$$

- $\tilde{\mathcal{A}}_k$ *concatenated set of multi-indices*:

$$\tilde{\mathcal{A}}_k := (\mathcal{A}_0, \mathcal{A}_1, \dots, \mathcal{A}_k);$$

- $\tilde{d}(k)$ *length of a concatenated set like $\tilde{\mathcal{A}}_k$* :

$$\tilde{d}(k) := d(0) + d(1) + \dots + d(k) = \frac{(d+k)!}{k!d!}.$$

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- \mathcal{P}_k , $k \in \mathbb{Z}_{\geq 0}$, **lexicographically ordered set of all monomials of total degree k** :

$$\mathcal{P}_k(x) := \left(x^{1\alpha}, \dots, x^{d(k)\alpha} \right), \quad x = (x_1, \dots, x_d), \quad (1\alpha, \dots, d(k)\alpha) = \mathcal{A}_k;$$

- \mathcal{P}_k^β , $\beta \in \mathbb{Z}_{\geq 0}^d$, **the set of monomials**:

$$\mathcal{P}_k^\beta(x) := \left(\binom{1\alpha}{\beta} x^{1\alpha - \beta}, \dots, \binom{d(k)\alpha}{\beta} x^{d(k)\alpha - \beta} \right), \quad (1\alpha, \dots, d(k)\alpha) = \mathcal{A}_k.$$

- \mathcal{D}_k , \mathcal{D}_k^β , $\beta \in \mathbb{Z}_{\geq 0}^d$, **ordered sets of differential operators**:

$$\mathcal{D}_k := \left((-i)^k D^{1\alpha}, \dots, (-i)^k D^{d(k)\alpha} \right),$$

$$\mathcal{D}_k^\beta := \left((-i)^{k-|\beta|} \binom{1\alpha}{\beta} D^{1\alpha - \beta}, \dots, (-i)^{k-|\beta|} \binom{d(k)\alpha}{\beta} D^{d(k)\alpha - \beta} \right).$$

- **concatenated sets of monomials**:

$$\tilde{\mathcal{P}}_k := (\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_k), \quad \tilde{\mathcal{P}}_k^\beta := (\mathcal{P}_0^\beta, \mathcal{P}_1^\beta, \dots, \mathcal{P}_k^\beta);$$

- **concatenated sets of derivatives**:

$$\tilde{\mathcal{D}}_k := (\mathcal{D}_0, \mathcal{D}_1, \dots, \mathcal{D}_k), \quad \tilde{\mathcal{D}}_k^\beta := (\mathcal{D}_0^\beta, \mathcal{D}_1^\beta, \dots, \mathcal{D}_k^\beta).$$

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Remark

If $\beta \not\leq \alpha$, then $[\mathcal{P}_k^\beta(x)]_q = [\mathcal{D}_k^\beta]_q = 0$. If $|\beta| > k$, then $\mathcal{P}_k^\beta(x)$, \mathcal{D}_k^β are zero sets.

- **concatenated sets of monomials**:

$$\tilde{\mathcal{P}}_k := (\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_k), \quad \tilde{\mathcal{P}}_k^\beta := (\mathcal{P}_0^\beta, \mathcal{P}_1^\beta, \dots, \mathcal{P}_k^\beta);$$

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$$\mathcal{P}_k^\beta(x) := \left(\binom{1\alpha}{\beta} x^{1\alpha - \beta}, \dots, \binom{d(k)\alpha}{\beta} x^{d(k)\alpha - \beta} \right), \quad (1\alpha, \dots, d(k)\alpha) = \mathcal{A}_k.$$

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$$\mathcal{D}_k := \left((-i)^k D^{1\alpha}, \dots, (-i)^k D^{d(k)\alpha} \right),$$

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Definition

Suppose $\mathbf{A} := [a_{ij}]$ ($1 \leq i \leq n, 1 \leq j \leq m$), $a_{ij} \in \mathbb{C}$, is an $n \times m$ matrix. By definition, put

$$\ker \mathbf{A} := \{\mathbf{v} \in \mathbb{C}^m : \mathbf{A}\mathbf{v} = \mathbf{0}\}.$$

We say that the linear space $\ker \mathbf{A}$ is the (right) null-space of the matrix \mathbf{A} .

Remark

Sometimes we shall treat the null-space $\ker \mathbf{A}$ as a $(\dim \ker \mathbf{A})$ -column matrix of vectors that the vectors form a basis for $\ker \mathbf{A}$.

For $l \in \mathbb{Z}_{\geq 0}$, define a $\tilde{d}(l) \times \tilde{d}(l)$ matrix \tilde{D}_l as

$$\begin{aligned} \tilde{D}_l &:= \begin{bmatrix} D_0 & D_1 & \dots & D_{l-1} & D_l \end{bmatrix} \\ &= \begin{bmatrix} D_0^0 & D_1^0 & \dots & D_{l-1}^0 & D_l^0 \\ 0 & D_1^1 & \dots & D_{l-1}^1 & D_l^1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & D_{l-1}^{l-1} & D_l^{l-1} \\ 0 & 0 & \dots & 0 & D_l^l \end{bmatrix}, \end{aligned} \quad (\spadesuit)$$

where $k \in \mathbb{Z}_{\geq 0}$, $k \leq l$, and a $\tilde{d}(l) \times d(k)$ matrix D_k defined as follows:

$$D_k := \begin{bmatrix} D_k^0 \\ D_k^1 \\ \vdots \\ D_k^k \\ \underbrace{0}_{\tilde{d}(l) - \tilde{d}(k)} \\ \vdots \\ 0 \end{bmatrix}, \quad \begin{array}{l} D_k^r, r = 0, \dots, k, \\ \text{are } d(r) \times d(k) \\ \text{submatrices defined} \\ \text{as} \end{array} \quad D_k^r := \begin{bmatrix} \mathcal{D}_k^{1\beta} \\ \mathcal{D}_k^{2\beta} \\ \vdots \\ \mathcal{D}_k^{d(r)\beta} \end{bmatrix}$$

$$\left({}^1\beta, \dots, {}^{d(r)}\beta \right) = \mathcal{A}_r.$$

For $l \in \mathbb{Z}_{\geq 0}$, define a $\tilde{d}(l) \times \tilde{d}(l)$ matrix \tilde{D}_l as

$$\begin{aligned} \tilde{D}_l &:= [D_0 \quad D_1 \quad \dots \quad D_{l-1} \quad D_l] \\ &= \begin{bmatrix} D_0^0 & D_1^0 & \dots & D_{l-1}^0 & D_l^0 \\ 0 & D_1^1 & \dots & D_{l-1}^1 & D_l^1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & D_{l-1}^{l-1} & D_l^{l-1} \\ 0 & 0 & \dots & 0 & D_l^l \end{bmatrix}, \end{aligned} \quad (\spadesuit)$$

where $k \in \mathbb{Z}_{\geq 0}$, $k \leq l$, and a $\tilde{d}(l) \times d(k)$ matrix D_k defined as follows:

$$\begin{aligned} D_k & \quad D_k^r \\ := \begin{bmatrix} D_k^0 \\ D_k^1 \\ \vdots \\ D_k^k \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad & := (-i)^{k-r} \begin{bmatrix} \left[\begin{array}{c} \binom{1\alpha}{1\beta} D^{1\alpha-1\beta} \dots \binom{d(k)\alpha}{1\beta} D^{d(k)\alpha-1\beta} \\ \binom{1\alpha}{2\beta} D^{1\alpha-2\beta} \dots \binom{d(k)\alpha}{2\beta} D^{d(k)\alpha-2\beta} \\ \dots \\ \binom{1\alpha}{d(r)\beta} D^{1\alpha-d(r)\beta} \dots \binom{d(k)\alpha}{d(r)\beta} D^{d(k)\alpha-d(r)\beta} \end{array} \right] \end{bmatrix} \\ \left. \begin{matrix} \tilde{d}(l) \\ \tilde{d}(k) \end{matrix} \right\} & \quad \left(\binom{1\beta}{\dots}, \dots, \binom{d(r)\beta}{\dots} \right) = \mathcal{A}_r, \quad \left(\binom{1\alpha}{\dots}, \dots, \binom{d(k)\alpha}{\dots} \right) = \mathcal{A}_k, \\ r = 0, 1, \dots, k & \quad k = 0, 1, \dots, l \end{aligned}$$

Component-wise form of the matrix \tilde{D}_l , $l \in \mathbb{Z}_{\geq 0}$ is:

$$[\tilde{D}_l]_{qr, 1 \leq q, r \leq \tilde{d}(l)} = \begin{cases} (-i)^{|r_\alpha - q_\beta|} \binom{r_\alpha}{q_\beta} D^{r_\alpha - q_\beta}, & q_\beta \leq r_\alpha, \\ 0, & \text{otherwise,} \end{cases}$$

where $({}^1\alpha, \dots, {}^{\tilde{d}(l)}\alpha) = ({}^1\beta, \dots, {}^{\tilde{d}(l)}\beta) = \tilde{\mathcal{A}}_l$.

2D $\tilde{d}(3) \times \tilde{d}(3) = 10 \times 10$ matrix \tilde{D}_3 is of the form:

$$\tilde{D}_3 := \left[\begin{array}{c|ccc|cccc} \mathbf{I} & -i\partial_x & -i\partial_y & -\partial_{xx} & -\partial_{xy} & -\partial_{yy} & i\partial_{xxx} & i\partial_{xxy} & i\partial_{xyy} & i\partial_{yyy} \\ \hline 0 & \mathbf{I} & 0 & -2i\partial_x & -i\partial_y & 0 & -3\partial_{xx} & -2\partial_{xy} & -\partial_{yy} & 0 \\ 0 & 0 & \mathbf{I} & 0 & -i\partial_x & -2i\partial_y & 0 & -\partial_{xx} & -2\partial_{xy} & -3\partial_{yy} \\ \hline 0 & 0 & 0 & \mathbf{I} & 0 & 0 & -3i\partial_x & -i\partial_y & 0 & 0 \\ 0 & 0 & 0 & 0 & \mathbf{I} & 0 & 0 & -2i\partial_x & -2i\partial_y & 0 \\ 0 & 0 & 0 & 0 & 0 & \mathbf{I} & 0 & 0 & -i\partial_x & -3i\partial_y \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & \mathbf{I} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \mathbf{I} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \mathbf{I} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \mathbf{I} \end{array} \right],$$

where \mathbf{I} is the identity operator.

$$\tilde{D}_I := \begin{bmatrix} D_0^0 & D_1^0 & \cdots & D_{I-1}^0 & D_I^0 \\ 0 & D_1^1 & \cdots & D_{I-1}^1 & D_I^1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & D_{I-1}^{I-1} & D_I^{I-1} \\ 0 & 0 & \cdots & 0 & D_I^I \end{bmatrix}. \quad (\spadesuit)$$

Proposition

Let $I \in \mathbb{Z}_{\geq 0}$. The submatrix

$$D_m^{m'} := (-i)^{m-m'} \begin{bmatrix} \begin{bmatrix} \binom{1\alpha}{1\beta} D^{1\alpha-1\beta} & \cdots & \binom{d(m)\alpha}{1\beta} D^{d(m)\alpha-1\beta} \\ \binom{1\alpha}{2\beta} D^{1\alpha-2\beta} & \cdots & \binom{d(m)\alpha}{2\beta} D^{d(m)\alpha-2\beta} \\ \dots & \dots & \dots \\ \binom{1\alpha}{d(m')\beta} D^{1\alpha-d(m')\beta} & \cdots & \binom{d(m)\alpha}{d(m')\beta} D^{d(m)\alpha-d(m')\beta} \end{bmatrix} \end{bmatrix},$$

$m' = 0, \dots, m$, $m = 0, \dots, I$, contains only the derivatives of order $m - m'$.

$$\tilde{D}_l := \begin{bmatrix} D_0^0 & D_1^0 & \dots & D_{l-1}^0 & D_l^0 \\ 0 & D_1^1 & \dots & D_{l-1}^1 & D_l^1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & D_{l-1}^{l-1} & D_l^{l-1} \\ 0 & 0 & \dots & 0 & D_l^l \end{bmatrix}. \quad (\spadesuit)$$

Proposition

Let $l \in \mathbb{Z}_{\geq 0}$. The submatrix $D_m^{m'}$ $m' = 0, \dots, m, m = 0, \dots, l$, contains only the derivatives of order $m - m'$.

Corollary

- 1 All the submatrices on the m th block diagonal of matrix (\spadesuit) , i. e., the submatrices $D_m^0, D_{m+1}^1, \dots, D_l^{l-m}$, contain the derivatives of order m ;

$$\tilde{D}_l := \begin{bmatrix} \mathbf{I} & \mathbf{D}_1^0 & \dots & \mathbf{D}_{l-1}^0 & \mathbf{D}_l^0 \\ \mathbf{0} & \mathbf{I} & \dots & \mathbf{D}_{l-1}^1 & \mathbf{D}_l^1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & \mathbf{I} & \mathbf{D}_l^{l-1} \\ \mathbf{0} & \mathbf{0} & \dots & \mathbf{0} & \mathbf{I} \end{bmatrix}. \quad (\spadesuit)$$

Proposition

Let $l \in \mathbb{Z}_{\geq 0}$. The submatrix $\mathbf{D}_m^{m'}$ $m' = 0, \dots, m$, $m = 0, \dots, l$, contains only the derivatives of order $m - m'$.

Corollary

- 1 All the submatrices on the m th block diagonal of matrix (\spadesuit) , i. e., the submatrices $\mathbf{D}_m^0, \mathbf{D}_{m+1}^1, \dots, \mathbf{D}_l^{l-m}$, contain the derivatives of order m ;
- 2 $\mathbf{D}_m^m = \mathbf{I}$, where \mathbf{I} is the $d(m) \times d(m)$ identity matrix.

$$\tilde{D}_I f(x_0) := \begin{bmatrix} If(x_0) & D_1^0 f(x_0) & \dots & D_{l-1}^0 f(x_0) & D_l^0 f(x_0) \\ 0 & If(x_0) & \dots & D_{l-1}^1 f(x_0) & D_l^1 f(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & If(x_0) & D_{l-1}^{l-1} f(x_0) \\ 0 & 0 & \dots & 0 & If(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Corollary

- 1 All the submatrices on the m th block diagonal of the matrix \tilde{D}_I , i. e., the submatrices $D_m^0, D_{m+1}^1, \dots, D_l^{l-m}$, contain the derivatives of order m ;
- 2 $D_m^m f(x_0) = If(x_0)$, where I is $d(m) \times d(m)$ identity matrix.

$$\tilde{D}_I f(x_0) := \begin{bmatrix} If(x_0) & D_1^0 f(x_0) & \dots & D_{l-1}^0 f(x_0) & D_l^0 f(x_0) \\ 0 & If(x_0) & \dots & D_{l-1}^1 f(x_0) & D_l^1 f(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & If(x_0) & D_{l-1}^{l-1} f(x_0) \\ 0 & 0 & \dots & 0 & If(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Corollary

- 1 All the submatrices on the m th block diagonal of the matrix \tilde{D}_I , i. e., the submatrices $D_m^0, D_{m+1}^1, \dots, D_{l-m}^{l-m}$, contain the derivatives of order m ;
- 2 $D_m^m f(x_0) = If(x_0)$, where I is $d(m) \times d(m)$ identity matrix.

Theorem

The matrix $\tilde{D}_I f(x_0)$, $l \in \mathbb{Z}_{\geq 0}$, see $(\spadesuit\spadesuit)$, is singular iff $f(x_0) = 0$.

Properties of the matrix $\tilde{D}_l f(x_0)$

$$\tilde{D}_l f(x_0) := \begin{bmatrix} If(x_0) & D_1^0 f(x_0) & \dots & D_{l-1}^0 f(x_0) & D_l^0 f(x_0) \\ 0 & If(x_0) & \dots & D_{l-1}^1 f(x_0) & D_l^1 f(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & If(x_0) & D_l^{l-1} f(x_0) \\ 0 & 0 & \dots & 0 & If(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Corollary

- 1 All the submatrices on the m th block diagonal of the matrix \tilde{D}_l , i. e., the submatrices $D_m^0, D_{m+1}^1, \dots, D_l^{l-m}$, contain the derivatives of order m ;
- 2 $D_m^m f(x_0) = If(x_0)$, where I is $d(m) \times d(m)$ identity matrix.

Theorem

The matrix $\tilde{D}_l f(x_0)$, $l \in \mathbb{Z}_{\geq 0}$, see $(\spadesuit\spadesuit)$, is singular iff $f(x_0) = 0$.

Theorem

The $d(m') \times d(m)$ submatrix $D_m^{m'} f(x_0)$, $m' = 0, \dots, m$, $m = 0, \dots, l$, $l \in \mathbb{Z}_{\geq 0}$, has full rank if and only if there exists at least one non-zero derivative $D^\gamma f(x_0)$, $|\gamma| = m - m'$.

$$\tilde{D}_l f(x_0) := \begin{bmatrix} If(x_0) & D_1^0 f(x_0) & \dots & D_{l-1}^0 f(x_0) & D_l^0 f(x_0) \\ 0 & If(x_0) & \dots & D_{l-1}^1 f(x_0) & D_l^1 f(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & If(x_0) & D_l^{l-1} f(x_0) \\ 0 & 0 & \dots & 0 & If(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Theorem

The matrix $\tilde{D}_l f(x_0)$, $l \in \mathbb{Z}_{\geq 0}$, see $(\spadesuit\spadesuit)$, is singular iff $f(x_0) = 0$.

Remark

Each of the submatrices $D_m^{m'} f(x_0)$, $m' = 0, \dots, m$, $m = 0, \dots, l$, is either a full rank matrix or zero matrix.

Let $P \in \Pi$, let $x_0 \in \mathbb{C}^d$, $l \in \mathbb{Z}_{\geq 0}$, then

$$\tilde{D}_l P(x_0) := \begin{bmatrix} IP(x_0) & D_1^0 P(x_0) & \dots & D_{l-1}^0 P(x_0) & D_l^0 P(x_0) \\ 0 & IP(x_0) & \dots & D_{l-1}^1 P(x_0) & D_l^1 P(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & IP(x_0) & D_l^{l-1} P(x_0) \\ 0 & 0 & \dots & 0 & IP(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Theorem

Let $l \in \mathbb{Z}_{\geq 0}$, $\tilde{\mathcal{P}}_l$ be the lexicographically ordered set of monomials.

Let $P \in \Pi$, $x_0 \in \mathbb{C}^d$ be a given point, $\tilde{D}_l P(x_0)$ be matrix $(\spadesuit\spadesuit)$, $v \in \mathbb{C}^{\tilde{d}(l)}$ be a vector. Then

$$\left. \begin{array}{l} e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_l(x)] v \neq 0, \\ e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_l(x)] v \in e^{ix_0 \cdot x} \Pi_{\leq l} \cap \ker P(-iD) \end{array} \right\} \iff \begin{cases} P(x_0) = 0, \\ v \in \ker \tilde{D}_l P(x_0) \end{cases}$$

Let $P \in \Pi$, let $x_0 \in \mathbb{C}^d$, $l \in \mathbb{Z}_{\geq 0}$, then

$$\tilde{D}_l P(x_0) := \begin{bmatrix} IP(x_0) & D_1^0 P(x_0) & \dots & D_{l-1}^0 P(x_0) & D_l^0 P(x_0) \\ 0 & IP(x_0) & \dots & D_{l-1}^1 P(x_0) & D_l^1 P(x_0) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & IP(x_0) & D_l^{l-1} P(x_0) \\ 0 & 0 & \dots & 0 & IP(x_0) \end{bmatrix}. \quad (\spadesuit\spadesuit)$$

Theorem

Let $l \in \mathbb{Z}_{\geq 0}$, $\tilde{\mathcal{P}}_l := (\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_l)$, $\mathcal{P}_k(x) := (x^{1\alpha}, \dots, x^{d(k)\alpha})$,
 $(1\alpha, \dots, d(k)\alpha) = \mathcal{A}_k$, $k = 0, \dots, l$.

Let $P \in \Pi$, $x_0 \in \mathbb{C}^d$ be a given point, $\tilde{D}_l P(x_0)$ be matrix $(\spadesuit\spadesuit)$, $v \in \mathbb{C}^{\tilde{d}(l)}$ be a vector. Then

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Lemma

Let $I \in \mathbb{Z}_{>0}$, $\tilde{\mathcal{D}}_I$ be the lexicographically ordered set of derivatives, \tilde{D}_I be matrix (\spadesuit), and functions f, g be sufficiently differentiable. Then

$$\boxed{[\tilde{\mathcal{D}}_I(fg)] = [\tilde{\mathcal{D}}_I f] \tilde{D}_I g = [\tilde{\mathcal{D}}_I g] \tilde{D}_I f} \quad (\star)$$

Remark

The proof of the previous lemma can be based on the Leibniz rule.

Sketch of the proof

- $\det [\tilde{D}_I P(x_0)] = 0 \iff P(x_0) = 0$
- Consider an expression

$$P(-iD) \left(e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_I(x)] v \right) \xrightarrow{\tilde{\mathcal{D}}_I} P(\xi) [\tilde{\mathcal{D}}_I \delta(\xi - x_0)] v.$$

For $\forall \phi \in \mathcal{S}(\mathbb{C}^d)$, the functional $\overline{\langle P [\tilde{\mathcal{D}}_I \delta(\cdot - x_0)] v, \phi \rangle}$ is of the form

$$\begin{aligned} \overline{\langle P [\tilde{\mathcal{D}}_I \delta(\cdot - x_0)] v, \phi \rangle} &= \overline{\langle \delta(\cdot - x_0), [\tilde{\mathcal{D}}_I (\overline{P\phi})] \bar{v} \rangle} \\ &= [\tilde{\mathcal{D}}_I (P(x_0) \overline{\phi(x_0)})] v \stackrel{\text{by } (\star)}{=} [\tilde{\mathcal{D}}_I \overline{\phi(x_0)}] [\tilde{D}_I P(x_0)] v. \end{aligned}$$

Sketch of the proof

- $\det [\tilde{D}_I P(x_0)] = 0 \iff P(x_0) = 0$
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Thus

$$\left. \begin{array}{l} e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_I(x)] v \neq 0, \\ e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_I(x)] v \in e^{ix_0 \cdot x} \Pi_{\leq I} \cap \ker P(-iD) \end{array} \right\} \iff \left\{ \begin{array}{l} P(x_0) = 0, \\ v \in \ker \tilde{D}_I P(x_0) \end{array} \right. \quad \square$$

Sketch of the proof

- For $\forall \phi \in \mathcal{S}(\mathbb{C}^d)$, the functional $\overline{\langle P [\tilde{\mathcal{D}}_I \delta(\cdot - x_0)] \mathbf{v}, \phi \rangle}$ is of the form

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Thus

$$\left. \begin{aligned} e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_I(x)] \mathbf{v} &\neq 0, \\ e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_I(x)] \mathbf{v} &\in e^{ix_0 \cdot x} \Pi_{\leq I} \cap \ker P(-iD) \end{aligned} \right\} \iff \begin{cases} P(x_0) = 0, \\ \mathbf{v} \in \ker \tilde{\mathcal{D}}_I P(x_0) \end{cases} \quad \square$$

- 1 A.Н. Колмогоров, С.В. Фомин. Элементы теории функций и функционального анализа. М.: Наука, 2004.

Remark

The previous proof can be transformed for other (linear and linear-conjugate, see for example [1]) functionals like $\overline{\langle \mathbf{f}, \phi \rangle}$.

Sketch of the proof

- For $\forall \phi \in \mathcal{S}(\mathbb{C}^d)$, the functional $\overline{\langle P [\tilde{\mathcal{D}}_I \delta(\cdot - x_0)] \mathbf{v}, \phi \rangle}$ is of the form

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- Kolmogorov A.N., Fomin S.V. Elements of the Theory of Functions and Function Analysis. Dover Books, New York (1957)

Remark

The previous proof can be transformed for other (linear and linear-conjugate, see for example [1]) functionals like $\overline{\langle \mathbf{f}, \phi \rangle}$.

Lemma (almost obvious)

Let $I \in \mathbb{Z}_{\geq 0}$, $\tilde{\mathcal{P}}_I$ be the lexicographically ordered set of monomials.

Let $\mathcal{V}_I \subseteq \Pi_{\leq I}$ be a space of polynomials. Then there is the linear space $V_I \subseteq \mathbb{C}^{\tilde{\mathcal{P}}(I)}$ such that

$$\mathcal{V}_I = \left\{ \left[\tilde{\mathcal{P}}_I \right] v : v \in V_I \right\}. \quad (*)$$

And vice versa.

Theorem (unproved yet)

Let $I \in \mathbb{Z}_{\geq 0}$, $P \in \Pi$, $x_0 \in \mathbb{C}^d$ be a given point. Let V_I be the linear space and \mathcal{V}_I be the polynomial space defined in the previous lemma. Then

$$e^{ix_0 \cdot x} \mathcal{V}_I = e^{ix_0 \cdot x} \Pi_{\leq I} \cap \ker P(-iD) \iff V_I = \ker \tilde{D}_I P(x_0). \quad (**)$$

Lemma (almost obvious)

Let $l \in \mathbb{Z}_{\geq 0}$, $\tilde{\mathcal{P}}_l := (\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_l)$, $\mathcal{P}_k(x) := (x^{1\alpha}, \dots, x^{d(k)\alpha})$,
 $(1\alpha, \dots, d(k)\alpha) = \mathcal{A}_k$, $k = 0, \dots, l$.

Let $\mathcal{V}_l \subseteq \Pi_{\leq l}$ be a space of polynomials. Then there is the linear space $V_l \subseteq \mathbb{C}^{\tilde{d}(l)}$ such that

$$\mathcal{V}_l = \left\{ [\tilde{\mathcal{P}}_l] v : v \in V_l \right\}. \quad (**)$$

And vice versa.

Theorem (unproved yet)

Let $l \in \mathbb{Z}_{\geq 0}$, $P \in \Pi$, $x_0 \in \mathbb{C}^d$ be a given point. Let V_l be the linear space and \mathcal{V}_l be the polynomial space defined in the previous lemma. Then

$$e^{ix_0 \cdot x} \mathcal{V}_l = e^{ix_0 \cdot x} \Pi_{\leq l} \cap \ker P(-iD) \iff V_l = \ker \tilde{D}_l P(x_0). \quad (**)$$

Theorem

Let $l \in \mathbb{Z}_{\geq 0}$. Let $P \in \Pi$, let x_0 be a root of P . Let $D^\alpha P(x_0)$, $\alpha \in \mathbb{Z}_{\geq 0}^d$, be a nonzero derivative of the least order. Then we have

$$\dim \left(e^{ix_0 \cdot x} \Pi_{\leq l} \cap \ker P(-iD) \right) = \begin{cases} \tilde{d}(l) - \tilde{d}(l - |\alpha|) & \text{if } l \geq |\alpha| > 0; \\ \tilde{d}(l) & \text{if } l < |\alpha|. \end{cases}$$

Moreover, if $l < |\alpha|$; then

$$e^{ix_0 \cdot x} \Pi_{\leq l} \cap \ker P(-iD) = e^{ix_0 \cdot x} \Pi_{\leq l}.$$

Let $P_{n'} \in \Pi$, $n' = 1, 2, \dots, n$. Then the system of PDE's is

$$\begin{cases} P_1(-iD) \cdot = 0, \\ \vdots \\ P_n(-iD) \cdot = 0. \end{cases} \quad (*)$$

Theorem

Let $l \in \mathbb{Z}_{\geq 0}$, $v \in \mathbb{C}^{\tilde{d}(l)}$, $x_0 \in \mathbb{C}^d$. Then

$$\left. \begin{aligned} & e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_l] v \neq 0, \\ & e^{ix_0 \cdot x} [\tilde{\mathcal{P}}_l] v \\ & \in e^{ix_0 \cdot x} \Pi_{\leq l} \cap \bigcap_{n'=1}^n \ker P_{n'}(-iD) \end{aligned} \right\} \iff \begin{cases} v \in \ker \begin{bmatrix} \tilde{D}_l P_1(x_0) \\ \vdots \\ \tilde{D}_l P_n(x_0) \end{bmatrix}, \\ P_1(x_0) \\ = \dots = P_n(x_0) = 0 \end{cases}$$

PDE with polynomial (multiplied by an exponential) right-hand side

x_0 is a root of polynomial P that the polynomial induces PDE

Theorem (based on Kronecker–Capelli (Rouché–Capelli) theorem)

- $P, F \in \Pi$; $x_0 \in \mathbb{C}^d$; $\underline{P(x_0) = 0}$; $F(x) := \left[\tilde{\mathcal{P}}_{\deg F}(x) \right] w$, $w \in \mathbb{C}^{\tilde{d}(\deg F)}$.
- Let D^α , $\alpha \in \mathbb{Z}_{\geq 0}^d$, be the least order derivative such that $D^\alpha P(x_0) \neq 0$.
- $l \in \mathbb{Z}_{\geq 0}$, $\boxed{l \geq \deg F + |\alpha|}$;
- let $V_l \subseteq \mathbb{C}^{\tilde{d}(l)}$ be a linear space and $\mathcal{V}_l \subseteq \Pi_{\leq l}$ be the corresponding polynomial space: $\mathcal{V}_l := \left\{ \left[\tilde{\mathcal{P}}_l \right] v : v \in V_l \right\}$.

Then

$$\forall p \in \mathcal{V}_l : P(-iD) \left(e^{ix_0 \cdot x} p \right) = e^{ix_0 \cdot x} F(x) \quad (*)$$

$$\begin{aligned} & \Updownarrow \\ \forall v \in V_l : \left[\tilde{D}_l P(x_0) \right] v &= \begin{bmatrix} w \\ \left\{ \begin{array}{c} 0 \\ \vdots \\ 0 \end{array} \right\} \\ \tilde{d}(l) - \tilde{d}(\deg F) \end{bmatrix}. \end{aligned} \quad (**)$$

Moreover,

- 1 $\dim V_l = \tilde{d}(l) - \tilde{d}(l - |\alpha|)$;
- 2 for any polynomial F such that $\deg F \leq l - |\alpha|$, linear system $(**)$ is consistent;
- 3 there exists a polynomial of arbitrary large degree to satisfy PDE $(*)$.

PDE with polynomial (multiplied by an exponential) right-hand side

x_0 is not root of polynomial P that the polynomial induces PDE

Theorem (based on Kronecker–Capelli (Rouché–Capelli) theorem)

- $P, F \in \Pi$; $x_0 \in \mathbb{C}^d$; $\underline{P(x_0) \neq 0}$; $F(x) := [\tilde{\mathcal{P}}_{\deg F}(x)] w$, $w \in \mathbb{C}^{\tilde{d}(\deg F)}$.
- $l \in \mathbb{Z}_{\geq 0}$, $\boxed{l \geq \deg F}$;
- let $V_l \subseteq \mathbb{C}^{\tilde{d}(l)}$ be a linear space and $\mathcal{V}_l \subseteq \Pi_{\leq l}$ be the corresponding polynomial space: $\mathcal{V}_l := \{[\tilde{\mathcal{P}}_l] v : v \in V_l\}$.

Then

$$\forall p \in \mathcal{V}_l : P(-iD) \left(e^{ix_0 \cdot x} p \right) = e^{ix_0 \cdot x} F(x) \quad (*)$$

$$\forall v \in V_l : [\tilde{D}_l P(x_0)] v = \begin{bmatrix} w \\ \underbrace{0 \\ \vdots \\ 0}_{\tilde{d}(l) - \tilde{d}(\deg F)} \end{bmatrix}. \quad (**)$$

Remark

If $P(x_0) \neq 0$, since the matrix $\tilde{D}_l P(x_0)$ is not singular, it follows that the polynomial p is defined uniquely and does not depend on the choice of l .

Definition

- Let the space $\mathbb{C}^{\tilde{d}(l)}$, $l \in \mathbb{Z}_{\geq 0}$, be the space with a Cartesian coordinate system:

$$\mathbb{C}^{\tilde{d}(l)} := \text{span} \left\{ \mathbf{e}_q : 1 \leq q \leq \tilde{d}(l) \right\},$$

where \mathbf{e}_q is a q th basis vector:
 $\mathbf{e}_q := (\delta_{q1}, \dots, \delta_{q, \tilde{d}(l)})$.

We can decompose $\mathbb{C}^{\tilde{d}(l)}$ as follows

$$\begin{aligned} \mathbb{C}^{\tilde{d}(l)} &= {}_0\mathbb{C}^{\tilde{d}(l)} \oplus {}_1\mathbb{C}^{\tilde{d}(l)} \oplus \dots \oplus {}_l\mathbb{C}^{\tilde{d}(l)}, \\ {}_j\mathbb{C}^{\tilde{d}(l)} &\perp {}_{j'}\mathbb{C}^{\tilde{d}(l)} \quad \text{if } j \neq j', \end{aligned} \quad (*)$$

where

$${}_0\mathbb{C}^{\tilde{d}(l)} := \text{span} \{ \mathbf{e}_1 \},$$

$${}_m\mathbb{C}^{\tilde{d}(l)} := \text{span} \left\{ \mathbf{e}_q : \tilde{d}(m-1) + 1 \leq q \leq \tilde{d}(m) \right\}, \quad m = 1, \dots, l.$$

Remark

Decomposition (*) corresponds to the block structure of matrix (\spadesuit) (as well as structures of $\tilde{\mathcal{P}}_l$ and $\tilde{\mathcal{D}}_l$).

Definition

- Let the space $\mathbb{C}^{\tilde{d}(l)}$, $l \in \mathbb{Z}_{\geq 0}$, be the space with a Cartesian coordinate system:

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- By \mathfrak{P}_m denote the orthogonal projection on the subspace ${}^m\mathbb{C}^{\tilde{d}(l)}$, $m = 0, \dots, l$; and define subspaces of the null-space $\mathbf{V}_l := \ker \tilde{\mathbf{D}}_l(x_0)$ as follows

$${}^m\mathbf{V}_l := \mathfrak{P}_m \mathbf{V}_l, \quad m = 0, 1, \dots, l. \quad (**)$$

Remark

The linear space \mathbf{V}_l can be presented as a sum, like (*), of the subspaces ${}^m\mathbf{V}_l$ only in the case of scale invariance of the corresponding polynomial space \mathcal{V}_l .

Definition

$$\mathbb{C}^{\tilde{d}(l)} := \text{span} \left\{ e_q : 1 \leq q \leq \tilde{d}(l) \right\},$$

$$e_q := \left(\delta_{q1}, \dots, \delta_{q, \tilde{d}(l)} \right).$$

$$\mathbb{C}^{\tilde{d}(l)} = {}^0\mathbb{C}^{\tilde{d}(l)} \oplus {}^1\mathbb{C}^{\tilde{d}(l)} \oplus \dots \oplus {}^l\mathbb{C}^{\tilde{d}(l)}. \quad (*)$$

$${}^m\mathbf{V}_l := \mathfrak{P}_m \mathbf{V}_l, \quad m = 0, 1, \dots, l. \quad (**)$$

Theorem (◇)

Let $l \in \mathbb{Z}_{\geq 0}$. Let the matrix $\tilde{\mathbf{D}}_l \mathbf{P}(x_0)$ be singular and $\mathbf{V}_l := \ker \tilde{\mathbf{D}}_l \mathbf{P}(x_0)$. Then the subspace ${}^l\mathbf{V}_l := \mathfrak{P}_l \mathbf{V}_l$ is nonzero.

- ④ Abramov S., Petkovšek M. On polynomial solutions of linear partial differential and (q -)difference equations. In: Computer Algebra in Scientific Computing. 14th International workshop LNCS 7442, 1–11 (2012)

Corollary (of Theorem ◇)

The null-space of the operator $\mathbf{P}(-i\mathbf{D})$ contains polynomials (multiplied by the exponential $e^{ix_0 \cdot x}$, where $\mathbf{P}(x_0) = \mathbf{0}$) of any degree. Thus we have a fundamental property, see [1], of polynomial solutions to a single constant coefficient PDE.

2D Laplace operator

$$L_1 := \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

The polynomial that induces the operator is

$$P_1(\xi, \eta) := -\xi^2 - \eta^2, \quad \xi, \eta \in \mathbb{C}.$$

15 × 15 matrix $\tilde{D}_4 P_1(0, 0)$ is of the form

$$\tilde{D}_4 P_1(0, 0) := \begin{bmatrix} 0 & 0 & 0 & 2 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 6 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 12 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned}
 & \left[\tilde{\mathcal{P}}_4 \right] \left[\ker \tilde{D}_4 P_1(0, 0) \right] \\
 &= \left[1 \mid x \quad y \mid x^2 \quad xy \quad y^2 \mid x^3 \quad x^2y \quad xy^2 \quad y^3 \mid x^4 \quad x^3y \quad x^2y^2 \quad xy^3 \quad y^4 \right]
 \end{aligned}$$

$$\times \begin{bmatrix}
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 \hline
 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 \hline
 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & -3 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 \hline
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -6 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}$$

$$= \left[1 \quad x \quad y \quad xy \quad y^2 - x^2 \quad 3xy^2 - x^3 \quad y^3 - 3x^2y \quad xy^3 - x^3y \quad x^4 - 6x^2y^2 + y^4 \right]$$

Examples

2D Laplace operator. Another root: $x_0 := (1, i)$

$$L_1 := \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

$$P_1(\xi, \eta) := -\xi^2 - \eta^2, \quad \xi, \eta \in \mathbb{C},$$

$$P_1(1, i) = 0.$$

- 1 Zakharov V.G. Reproducing solutions to PDEs by scaling functions. Int. J. Wavelets Multiresolut. Inf. Process. 3, 2050017 (2020)

$$L_1 := \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

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- ④ Zakharov V.G. Reproducing solutions to PDEs by scaling functions. Int. J. Wavelets Multiresolut. Inf. Process. 3, 2050017 (2020)

15 × 15 matrix $\tilde{D}_4 P_1(1, i)$ is of the form

0	2i	-2	2	0	2	0	0	0	0	0	0	0	0	0
0	0	0	4i	-2	0	6	0	2	0	0	0	0	0	0
0	0	0	0	2i	-4	0	2	0	6	0	0	0	0	0
0	0	0	0	0	0	6i	-2	0	0	12	0	2	0	0
0	0	0	0	0	0	0	4i	-4	0	0	6	0	6	0
0	0	0	0	0	0	0	0	2i	-6	0	0	2	0	12
0	0	0	0	0	0	0	0	0	0	8i	-2	0	0	0
0	0	0	0	0	0	0	0	0	0	0	6i	-4	0	0
0	0	0	0	0	0	0	0	0	0	0	0	4i	-6	0
0	0	0	0	0	0	0	0	0	0	0	0	0	2i	-8
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

$$L_1 := \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

$$P_1(1, i) = 0.$$

- ④ Zakharov V.G. Reproducing solutions to PDEs by scaling functions. Int. J. Wavelets Multiresolut. Inf. Process. 3, 2050017 (2020)

$$\begin{aligned} & e^{ix-y} \Pi_{\leq 4} \cap \ker L_1 \\ &= e^{ix-y} \operatorname{span} \left\{ 1, y - ix, -x^2 - 2ixy + y^2, ix^3 - 3x^2y - 3ixy^2 + y^3, \right. \\ & \quad \left. x^4 + 4ix^3y - 6x^2y^2 - 4ixy^3 + y^4 \right\}. \end{aligned} \quad (*)$$

Remark

If real or imaginary parts of the polynomials in (*) (compare with

$$\Pi_{\leq 4} \cap \ker L_1 = \Pi_{\leq 1} \oplus \operatorname{span} \left\{ xy, y^2 - x^2, 3xy^2 - x^3, y^3 - 3x^2y, \right. \\ \left. xy^3 - x^3y, x^4 - 6x^2y^2 + y^4 \right\}$$

multiplied by an exponential, then these parts are not solutions to the Laplace operator.

- ① Zakharov V.G. Reproducing solutions to PDEs by scaling functions. Int. J. Wavelets Multiresolut. Inf. Process. 3, 2050017 (2020)

$$L_{\text{sh}} = \left(\frac{\partial}{\partial x} - \mathbf{I} \right)^2 + \left(\frac{\partial}{\partial y} - i\mathbf{I} \right)^2, \quad \text{where } \mathbf{I} \text{ is the identity operator}$$

$$P_{\text{sh}}(\xi, \eta) := (i\xi - 1)^2 + (i\eta - i)^2$$

15×15 matrix $\tilde{D}_4 P_{\text{sh}}(-i, 1)$ is of the form

$$\begin{bmatrix} 0 & 0 & 0 & 2 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 6 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 12 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Examples

The Laplace operator shifted by a vector $(1, i)$

$$L_{\text{sh}} = \left(\frac{\partial}{\partial x} - \mathbf{I} \right)^2 + \left(\frac{\partial}{\partial y} - i\mathbf{I} \right)^2, \quad \text{where } \mathbf{I} \text{ is the identity operator}$$

$$P_{\text{sh}}(\xi, \eta) := (i\xi - 1)^2 + (i\eta - i)^2, \quad P_1(\xi, \eta) := -\xi^2 - \eta^2.$$

$$\tilde{D}_4 P_{\text{sh}}(-i, 1) := \begin{bmatrix} 0 & 0 & 0 & 2 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 6 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 12 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\tilde{D}_4 P_1(0, 0) := \begin{bmatrix} 0 & 0 & 0 & 2 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 6 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 12 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- ④ Zakharov V.G. Reproducing solutions to PDEs by scaling functions. Int. J. Wavelets Multiresolut. Inf. Process. 3, 2050017 (2020)

$$L_1 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2},$$

$$L_{\text{sh}} = \left(\frac{\partial}{\partial x} - \mathbf{I} \right)^2 + \left(\frac{\partial}{\partial y} - i\mathbf{I} \right)^2, \quad \text{where } \mathbf{I} \text{ is the identity operator}$$

$$P_{\text{sh}}(\xi, \eta) := (i\xi - 1)^2 + (i\eta - i)^2$$

$$\tilde{D}_4 P_{\text{sh}}(-i, 1) := \left[\begin{array}{ccc|ccc|cccc|cccc} 0 & 0 & 0 & 2 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 6 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 12 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2 & 0 & 12 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$e^{x+iy} \Pi_{\leq 4} \cap L_{\text{sh}} = e^{x+iy} \left(\Pi_{\leq 4} \cap L_1 \right)$$

$$\begin{cases} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = 0, \\ \frac{\partial^2}{\partial x \partial y} + \frac{\partial^2}{\partial x \partial z} + \frac{\partial^2}{\partial y \partial z} = 0. \end{cases}$$

- ① Pedersen P. A basis for polynomial solutions to systems of linear constant coefficient PDE's. Adv. Math. 117, 157–163 (1996)

$$\begin{cases} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = 0, \\ \frac{\partial^2}{\partial x \partial y} + \frac{\partial^2}{\partial x \partial z} + \frac{\partial^2}{\partial y \partial z} = 0. \end{cases}$$

Polynomials: $P_1(\xi, \eta, \zeta) := -\xi^2 - \eta^2 - \zeta^2$, $P_2(\xi, \eta, \zeta) := -\xi\eta - \xi\zeta - \eta\zeta$.

40×20 matrix $\begin{bmatrix} \tilde{D}_3 P_1(0, 0, 0) \\ \tilde{D}_3 P_2(0, 0, 0) \end{bmatrix}$ is of the form

0	0	0	0	2	0	2	0	0	2	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	6	0	2	0	0	0	0	2	0	0
0	0	0	0	0	0	0	0	0	0	0	2	0	6	0	0	0	0	2	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	0	2	0	0	6
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
...
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	1	0	1	1	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	2	0	0	2	1	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	1	2	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	2	2	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
...
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

$$\begin{cases} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = 0, \\ \frac{\partial^2}{\partial x \partial y} + \frac{\partial^2}{\partial x \partial z} + \frac{\partial^2}{\partial y \partial z} = 0. \end{cases}$$

- ① Pedersen P. A basis for polynomial solutions to systems of linear constant coefficient PDE's. Adv. Math. 117, 157–163 (1996)

Polynomials: $P_1(\xi, \eta, \zeta) := -\xi^2 - \eta^2 - \zeta^2$, $P_2(\xi, \eta, \zeta) := -\xi\eta - \xi\zeta - \eta\zeta$.

Basis of the space $\Pi_{\leq 3} \cap \ker P_1(-iD) \cap \ker P_2(-iD)$ is of the form

$$\left\{ 1, x, y, z, y^2 - x^2, xz - xy, yz - xy, z^2 - x^2, \right. \\ 3x^2y - 3x^2z - y^3 + z^3, -x^3 + 3x^2y + 3xy^2 - 6xyz - 2y^3 + 3yz^2, \\ -2x^3 + 3x^2y + 3xy^2 - 6xyz + 3xz^2 - y^3, \\ \left. x^3 + 3x^2y - 3x^2z - 3xy^2 - y^3 + 3y^2z \right\}.$$

- ④ de Boor C. The polynomials in the linear span of integer translates of a compactly supported function. *Constr. Approx.* 3, 199–208 (1987)

$$\mathcal{V}_{\text{de Boor}} := \text{span} \{1, y, x + y^2\},$$

$$L_3 := 2 \frac{\partial}{\partial x} - \frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

$$P_3(\xi, \eta) := 2i\xi + \xi^2 + \eta^2, \quad \xi, \eta \in \mathbb{C}.$$

15 × 15 matrix $\tilde{D}_4 P_3(0, 0)$ is of the form

0	2	0	-2	0	-2	0	0	0	0	0	0	0	0	0
0	0	0	4	0	0	-6	0	-2	0	0	0	0	0	0
0	0	0	0	2	0	0	-2	0	-6	0	0	0	0	0
0	0	0	0	0	0	6	0	0	0	-12	0	-2	0	0
0	0	0	0	0	0	0	4	0	0	0	-6	0	-6	0
0	0	0	0	0	0	0	0	2	0	0	0	-2	0	-12
0	0	0	0	0	0	0	0	0	0	8	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	6	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	4	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	2	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

$$L_3 := 2 \frac{\partial}{\partial x} - \frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial y^2}, \quad x, y \in \mathbb{R}.$$

$$P_3(\xi, \eta) := 2i\xi + \xi^2 + \eta^2, \quad \xi, \eta \in \mathbb{C}.$$

$$\left[\tilde{\mathcal{P}}_4 \right] \left[\ker \tilde{D}_4 P_3(0, 0) \right]$$

$$= \left[\begin{array}{c|cccc} 1 & x & y & x^2 & xy & y^2 & x^3 & x^2y & xy^2 & y^3 & x^4 & x^3y & x^2y^2 & xy^3 & y^4 \end{array} \right]$$

$$\times \left[\begin{array}{ccccc} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 1 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$= \left[\begin{array}{cccc} 1 & y & x + y^2 & 3xy + y^3 \\ 3x^2 + 6xy^2 + 3x + y^4 & & & \end{array} \right]$$

A Poisson equation is:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) p(x, y) = e^{ix-y} (-2xy + 3x + y^2 + 2) \quad (*)$$

$$P(\xi, \eta) := -\xi^2 - \eta^2, \quad w := [2 \quad 3 \quad 0 \quad 0 \quad -2 \quad 1]^T,$$

$$\begin{aligned} F(x, y) &:= -2xy + 3x + y^2 + 2 = [\tilde{\mathcal{P}}_2(1, i)] w \\ &= [1 \quad x \quad y \quad x^2 \quad xy \quad y^2] [2 \quad 3 \quad 0 \quad 0 \quad -2 \quad 1]^T. \end{aligned}$$

$$l := 3 \geq \deg F + |\alpha| = 2 + 1 = 3.$$

The corresponding linear algebraic equation $[\tilde{D}_3 P(1, i)] v = [w^T, 0, \dots, 0]^T$ is:

$$\left[\begin{array}{ccc|ccc|cccc} 0 & 2i & -2 & 2 & 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4i & -2 & 0 & 6 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2i & -4 & 0 & 2 & 0 & 6 \\ 0 & 0 & 0 & 0 & 0 & 0 & 6i & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 4i & -4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2i & -6 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] v = \begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \\ -2 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad (**)$$

A Poisson equation is:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) p(x, y) = e^{ix-y} (-2xy + 3x + y^2 + 2) \quad (*)$$

$$\left[\begin{array}{ccc|ccc|cccc} 0 & 2i & -2 & 2 & 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4i & -2 & 0 & 6 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2i & -4 & 0 & 2 & 0 & 6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 6i & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 4i & -4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 2i & -6 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] v = \begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \\ -2 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad (**)$$

Solution to algebraic equation (**),

$\dim \ker [\tilde{D}_3 P(1, i)] = \tilde{d}(3) - \tilde{d}(3-1) = d(3) = 4$, is:

$$v = \left(v_0, v_1, iv_1 + \left(\frac{5}{4} + \frac{i}{4} \right), -v_5 + \left(\frac{1}{4} + \frac{i}{4} \right), \left(-\frac{1}{2} - \frac{i}{2} \right) (-1 + (2 + 2i)v_5), v_5, \right. \\ \left. \left(\frac{1}{6} + \frac{i}{6} \right) (-1 + (3 + 3i)v_9), -3v_9 + \left(\frac{1}{2} - \frac{i}{2} \right), -\frac{1}{2}i(6v_9 - 1), v_9 \right),$$

$$v_0, v_1, v_5, v_9 \in \mathbb{C}.$$

A Poisson equation is:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) p(x, y) = e^{ix-y} (-2xy + 3x + y^2 + 2) \quad (*)$$

Solution to algebraic equation (**) is:

$$v = \left(v_0, v_1, iv_1 + \left(\frac{5}{4} + \frac{i}{4} \right), -v_5 + \left(\frac{1}{4} + \frac{i}{4} \right), \left(-\frac{1}{2} - \frac{i}{2} \right) (-1 + (2 + 2i)v_5), v_5, \right. \\ \left. \left(\frac{1}{6} + \frac{i}{6} \right) (-1 + (3 + 3i)v_9), -3v_9 + \left(\frac{1}{2} - \frac{i}{2} \right), -\frac{1}{2}i(6v_9 - 1), v_9 \right), \\ v_0, v_1, v_5, v_9 \in \mathbb{C}.$$

Solution to PDE (*) is:

$$p(x, y) = e^{ix-y} \left[\tilde{\mathcal{P}}_3(x, y) \right] v = e^{ix-y} \left(\left(\frac{1}{6} + \frac{i}{6} \right) (-1 + (3 + 3i)v_9)x^3 \right. \\ \left. + v_5 (-x^2 - 2ixy + y^2) + \left(-3v_9 + \left(\frac{1}{2} - \frac{i}{2} \right) \right) x^2y - \frac{1}{2}i(6v_9 - 1)xy^2 \right. \\ \left. + v_1(x + iy) + v_9y^3 + v_0 + \left(\frac{1}{4} + \frac{i}{4} \right) x^2 + \left(\frac{1}{2} + \frac{i}{2} \right) xy + \left(\frac{5}{4} + \frac{i}{4} \right) y \right), \\ v_0, v_1, v_5, v_9 \in \mathbb{C}.$$

Another Poisson equation is:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) p(x, y) = e^{y-x} (-2xy + 3x + y^2 + 2) \quad (*)$$

$$P(\xi, \eta) := -\xi^2 - \eta^2, \quad w := [2 \quad 3 \quad 0 \quad 0 \quad -2 \quad 1]^T,$$

$$\begin{aligned} F(x, y) &:= -2xy + 3x + y^2 + 2 = [\tilde{\mathcal{P}}_2(1, i)] w \\ &= [1 \quad x \quad y \quad x^2 \quad xy \quad y^2] [2 \quad 3 \quad 0 \quad 0 \quad -2 \quad 1]^T. \end{aligned}$$

$$l := 2 \geq \deg F = 2.$$

The corresponding linear algebraic equation $[\tilde{\mathcal{D}}_2 P(i, -i)] v = w$ is:

$$\left[\begin{array}{c|ccc|ccc} -2 & 2 & -2 & -2 & 0 & -2 \\ 0 & -2 & 0 & 4 & -2 & 0 \\ 0 & 0 & -2 & 0 & 2 & -4 \\ 0 & 0 & 0 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & -2 \end{array} \right] v = \begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \\ -2 \\ 1 \end{bmatrix} \quad (**)$$

Another Poisson equation is:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) p(x, y) = e^{y-x} (-2xy + 3x + y^2 + 2) \quad (*)$$

$P(i, -i) \neq 0$

$$\left[\begin{array}{ccc|ccc} -2 & 2 & -2 & -2 & 0 & -2 \\ 0 & -2 & 0 & 4 & -2 & 0 \\ 0 & 0 & -2 & 0 & 2 & -4 \\ \hline 0 & 0 & 0 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & -2 \end{array} \right] v = \begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \\ -2 \\ 1 \end{bmatrix} \quad (**)$$

Unique solutions to algebraic equation (**) and PDE (*) are:

$$v := \left(-5, -\frac{5}{2}, 2, 0, 1, -\frac{1}{2}\right),$$

$$p(x, y) := e^{y-x} \left(xy - \frac{5x}{2} - \frac{y^2}{2} + 2y - 5\right)$$

- **Now I have got a draft program (8,9 lines of code) on Wolfram Mathematica to obtain a polynomial basis of any dimension to solve any constant coefficient PDE (system of PDE's).**

I shall try to obtain:

- ... **matrix methods of polynomial solutions to PDE('s) with polynomial coefficients**;
- ... matrix methods of investigation of polynomial solutions to systems of constant coefficient PDE's;
- ... matrix methods of investigation of affine invariance/no invariance of a polynomial solution space to constant coefficient PDE('s).
- Also I would like to supply my computer code in Mathematica by some interface and maintenance.

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To be continued...