

# On summation of $P$ -recursive sequences\*

*S. A. Abramov*

Russian Academy of Sciences  
Dorodnicyn Computing Centre  
Vavilova 40, 119991, Moscow GSP-1, Russia  
`sabramov@ccas.ru`

## Abstract

We consider sequences which satisfy a linear recurrence equation  $Ly = 0$  with polynomial coefficients. A criterion, i.e., a necessary and sufficient condition is proposed for validity of the discrete Newton-Leibniz formula when a primitive (an indefinite sum)  $Rt$  of a solution  $t$  of  $Ly = 0$  is obtained either by Gosper's algorithm or by the Accurate Summation algorithm (the operator  $R$  has rational-function coefficients,  $\text{ord } R = \text{ord } L - 1$ ; in the Gosper case  $\text{ord } L = 1$ ,  $\text{ord } R = 0$ ). Additionally we show that if Gosper's algorithm succeeds on  $L$ ,  $\text{ord } L = 1$ , then  $Ly = 0$  *always* has some non-zero solutions  $t$ , defined everywhere, such that the discrete Newton-Leibniz formula  $\sum_{k=v}^w t(k) = u(w+1) - u(v)$  is valid for  $u = Rt$  and any integer bounds  $v \leq w$ .

## 1 Introduction

Let  $K$  be a field of characteristic zero. If  $t(k)$  is a  $K$ -valued sequence, then  $Et(k)$  is the sequence  $s(k) = t(k+1)$ . We consider  $P$ -recursive sequences, i.e., sequences, that satisfy recurrence equations of the form  $Ly = 0$ , where

$$L = a_\rho(k)E^\rho + a_{\rho-1}(k)E^{\rho-1} + \cdots + a_0(k), \quad (1)$$

$\rho \geq 1$ ,  $a_\rho(k), a_{\rho-1}(k), \dots, a_0(k) \in K[k]$ ,  $a_\rho(k)a_0(k) \neq 0$  and  $\gcd(a_0(k), \dots, a_{\rho-1}(k), a_\rho(k)) = 1$ . If  $\text{ord } L = \rho = 1$ , then the corresponding  $P$ -recursive sequences are *hypergeometric terms*.

---

\*Partially supported by RFBR under grant 04-01-00757.

In [4] we discussed validity of the discrete Newton-Leibniz formula when an indefinite sum of the sequence  $t(k)$  is obtained either by Gosper's algorithm [5] or by the Accurate Summation algorithm [3]. These algorithms, which we denote hereafter by  $\mathcal{GA}$  and  $\mathcal{AS}$ , respectively, search for a solution  $u$  of the *telescoping equation*

$$Eu(k) - u(k) = t(k) \quad (2)$$

where the sequence  $t(k)$  is  $P$ -recursive and satisfies  $Lt = 0$ . Suppose that using one of these algorithms we found a linear recurrence operator  $R$  of order  $\text{ord} L - 1$  with rational-function coefficients, such that  $u = Rt$  is a solution of (2) for some solution  $t$  of  $Lt = 0$  (in the Gosper case  $\text{ord} L = 1$  and  $\text{ord} R = 0$ , i.e.,  $R$  is a rational function). Then the question is: can we use the discrete Newton-Leibniz formula

$$\sum_{k=v}^w t(k) = u(w+1) - u(v) \quad (3)$$

to find the definite sum of values of  $t$ ? It was shown in [4] that sometimes (3) is not valid even when all of  $t(v), t(v+1), \dots, t(w), u(v), u(w+1)$  are defined. The reason is that equation (2) may fail to hold at certain points  $k$  of the summation interval.

Both  $\mathcal{GA}$ ,  $\mathcal{AS}$  start by constructing the minimal annihilator  $L$  of a given concrete sequence  $t$  and this step is not formalized. On the next steps these algorithms work with  $L$  only, while the sequence  $t$  itself is ignored (more precisely, in the case of  $\text{ord} L = 1$ ,  $L = a_1(k)E + a_0(k)$ ,  $\mathcal{GA}$  works with the certificate of  $t$ , i.e., with the rational function  $-\frac{a_0(k)}{a_1(k)}$ ). The algorithms try to construct an operator  $R$  such that  $u = Rt$  in (2).

If  $L$  is of type (1) then denote by  $V(L)$  the space of all sequences  $t(k)$  defined for all  $k \in \mathbb{Z}$  and such that  $Lt = 0$ . If additionally  $R$  is obtained from  $L$  either by  $\mathcal{GA}$  or by  $\mathcal{AS}$ , then denote by  $V_R(L)$  the subspace of  $V(L)$  which contains  $t \in V(L)$  iff formula (3) is valid for any integer  $v \leq w$  with  $u = Rt$ .

It may be that  $\dim V_R(L) < \dim V(L)$  (notice that quite often  $\dim V(L) > \text{ord} L$ ; it is possible that  $\dim V_R(L) > \text{ord} L$  as well).

In [4] some sufficient conditions for validity of (3) for a given sequence were given. In this paper we present a criterion, i.e., a necessary and sufficient condition for validity of this formula for all  $k \in \mathbb{Z}$  when  $u = Rt$ , and  $R$  is obtained either by  $\mathcal{GA}$  or by  $\mathcal{AS}$ . Note that (3) is valid for all integer bounds  $v \leq w$  iff (2) is valid for all  $k \in \mathbb{Z}$ . In addition, if  $R$  is obtained either

by  $\mathcal{GA}$  or by  $\mathcal{AS}$ , then we present a description of the linear space  $V_R(L)$ , and prove that in the case of  $\text{ord} L = 1$  the dimension of  $V_R(L)$  is always positive.

We assume that  $K = \mathbb{C}$  in all examples of this paper.

**Example 1**  $\mathcal{GA}$  succeeds on the operator  $L = kE - (k+1)^2$ , and the result is  $R = \frac{1}{k}$ . The space  $V(L)$  is two-dimensional: the sequences

$$t_1(k) = \begin{cases} 0, & \text{if } k < 0, \\ k \cdot k!, & \text{if } k \geq 0 \end{cases}$$

and

$$t_2(k) = \begin{cases} \frac{(-1)^k k}{(-k-1)!}, & \text{if } k < 0, \\ 0, & \text{if } k \geq 0 \end{cases}$$

form a basis of  $V(L)$ . Our criterion says that, generally speaking, (3) is not applicable to  $t_1$ , but is applicable to  $t_2$ . We can illustrate this as follows. Applying (3) to  $t_1$  with  $v = -1, w = 1$ , we have

$$t_1(-1) + t_1(0) + t_1(1) = \frac{1}{k} t_1(k) \big|_{k=2} - \frac{1}{k} t_1(k) \big|_{k=-1} = \frac{1}{2} \cdot 4 - 0 = 2$$

which is wrong, because  $t_1(-1) + t_1(0) + t_1(1) = 0 + 0 + 1 = 1$ . Applying (3) to  $t_2$  with the same  $v, w$ , we have

$$t_2(-1) + t_2(0) + t_2(1) = \frac{1}{k} t_2(k) \big|_{k=2} - \frac{1}{k} t_2(k) \big|_{k=-1} = 0 - (-1) = 1$$

which is correct, because  $t_2(-1) + t_2(0) + t_2(1) = 1 + 0 + 0 = 1$ .

Our algorithm computes a basis of the subspace  $V_R(L)$ . In Example 1  $V_R(L)$  is one-dimensional and is generated by  $t_2$ . Examples which demonstrate that sometimes this dimension can be greater than 1 are given (see Examples 2, 4).

## 2 Preliminaries

For  $f(k), g(k) \in K[k]$  we write  $f(k) \perp g(k)$  to indicate that  $f(k)$  and  $g(k)$  are coprime. If  $r(k) \in K(k)$ , then  $\text{den}(r(k))$  is the monic polynomial from  $K[k]$  such that  $r(k) = \frac{f(k)}{\text{den}(r(k))}$  for some  $f(k) \in K[k]$ ,  $f(k) \perp \text{den}(r(k))$ . If  $L$  and  $M$  are linear recurrence operators with coefficients from  $K(k)$  then we write

$L \circ M$  for the product of  $L$  and  $M$  in the non-commutative ring  $K(k)[E]$ . If  $M = r(k)$  is a rational function, then  $L \circ r(k)$  is an operator of the same order as  $L$ , while  $Lr(k)$  is a rational function (the result of applying  $L$  to  $r(k)$ ).

The algorithm  $\mathcal{AS}$  starts with finding a rational function solution  $r(k)$  of the equation  $L^*y = 1$  (say, by the algorithms from [1] or [2]), where  $L^*$  is the adjoint of  $L$ :

$$L^* = a_\rho(k - \rho)E^{-\rho} + a_{\rho-1}(k - \rho + 1)E^{-\rho+1} + \cdots + a_0(k).$$

The equation satisfied by the rational function  $r(k)$  can be rewritten as

$$a_0(k + \rho)r(k + \rho) + a_1(k + \rho - 1)r(k + \rho - 1) + \cdots + a_\rho(k)r(k) = 1. \quad (4)$$

If such  $r(k)$  exists then  $R$  can be found from the relation

$$1 - rL = (E - 1) \circ R. \quad (5)$$

We obtain

$$R = c_{\rho-1}(k)E^{\rho-1} + c_{\rho-2}(k)E^{\rho-2} + \cdots + c_0(k), \quad (6)$$

where

$$c_i(k) = \sum_{j=0}^i r(k + j)a_{i-j}(k + j) - 1 \quad (7)$$

for  $0 \leq i \leq \rho - 1$ .

$\mathcal{GA}$  works with the case  $\rho = 1$ ,

$$L = a_1(k)E + a_0(k), \quad a_1(k), a_0(k) \in K[k], \quad a_1(k) \perp a_0(k), \quad (8)$$

and tries to construct  $r'(k) \in K(k)$  such that

$$a_0(k)r'(k + 1) + a_1(k)r'(k) = -a_1(k) \quad (9)$$

(this can also be done by the algorithms from [1] or [2]). If such  $r'$  exists then  $R = r'$ .

If  $L$  is as in (8), then  $\mathcal{GA}$  succeeds on  $L$  iff  $\mathcal{AS}$  does: if  $\rho = 1$  and  $r(k)$  is a rational solution of (4), then (8) has the rational solution

$$r'(k) = -r(k - 1)a_1(k - 1). \quad (10)$$

In this case both  $\mathcal{AS}$  and  $\mathcal{GA}$  produce the same operator (rational function)  $R = r'$ .

Let  $\rho \geq 1$  and suppose that there exists

$$r(k) = \frac{s(k)}{q(k)}, \quad s(k) \perp q(k), \quad (11)$$

which satisfies (4). Let  $R$  be the result of applying  $\mathcal{AS}$  to  $L$  of the type (1), and let a polynomial  $d \in K[k]$  and an operator  $B \in K[k, E]$  with relatively prime coefficients be such that

$$E^\rho \circ L^* \circ \frac{1}{q} = \frac{1}{d} B. \quad (12)$$

Set

$$p(k) = d(k - \rho), \quad (13)$$

$$\bar{L} = B^* \circ E^\rho. \quad (14)$$

Then one gets

$$L \circ p = q \bar{L} \quad (15)$$

and

$$R \circ p \in K[k, E] \quad (16)$$

(this was deduced in [4]).

### 3 $\mathcal{AS}$ and the discrete Newton-Leibniz formula

The following sufficient condition for validity of (3) is a consequence of Theorem 5 from [4]: If a  $K$ -valued sequence  $\bar{t}(k)$  is defined and satisfies  $\bar{L}\bar{t} = 0$  for all  $k \in \mathbb{Z}$ , then  $t = p\bar{t}$  satisfies  $Lt = 0$  for all  $k$ , and the discrete Newton-Leibniz formula (3) can be applied to  $t$  with  $u = Rt = (R \circ p)\bar{t}$  and any integer bounds  $v \leq w$ . In this section we prove also the necessity of this condition.

Let  $R$  be an operator of type (6). We call the monic polynomial

$$\text{den}(R) = \text{lcm}(\text{den}(c_{\rho-1}(k - \rho + 1)), \text{den}(c_{\rho-2}(k - \rho + 2)), \dots, \text{den}(c_0(k)))$$

the *denominator* of  $R$ . It is evident that the operator  $R \circ \text{den}(R)$  has polynomial coefficients (i.e., belongs to  $K[k, E]$ ).

In the rest of this paper we suppose that the operator  $R$  can be applied to a sequence  $t$  only if the sequence  $t$  is represented in the form

$$t = \text{den}(R)t', \quad (17)$$

where  $t'$  is a sequence defined for all  $k$ . In this case we compute the value of  $Rt$  for any integer  $k$  as the value of the sequence  $(R \circ \text{den}(R))t'$ . If a sequence  $t(k)$  is defined for all  $k$  and annihilated by an operator from  $K[k, E]$ , and if  $\mathcal{AS}$  or  $\mathcal{GA}$  is applicable to the minimal annihilator of this sequence returning an operator  $R$  as result, then  $t$  has to be represented in the form (17) before using (3) with  $u = Rt$  (in the case where  $\text{den}(R)$  has integer zeros, the application of  $R$  to  $t$  is not possible without such representation).

Certainly, representation (17) does not guarantee that (3) gives the correct result.

**Proposition 1** *Let  $L$  be of the type (1),  $r = \frac{s}{q}$  satisfy (4), and let  $R$  satisfy (5). Then  $\text{den}(R) = p$ , where the polynomial  $p$  is as in (13).*

**Proof:** First we show that

$$p \mid \text{den}(R). \quad (18)$$

We have

$$E^\rho \circ L^* \circ \frac{1}{q} = \frac{a_0(k+\rho)}{q(k+\rho)}E^\rho + \dots + \frac{a_{\rho-1}(k+1)}{q(k+1)}E + \frac{a_\rho(k)}{q(k)} \quad (19)$$

(notice that the coefficients of  $E^i$ 's in the right-hand side of (19) may be reducible). By (12)

$$d(k) \mid \text{lcm} \left( \text{den} \left( \frac{a_\rho(k)}{q(k)} \right), \text{den} \left( \frac{a_{\rho-1}(k+1)}{q(k+1)} \right), \dots, \text{den} \left( \frac{a_0(k+\rho)}{q(k+\rho)} \right) \right).$$

Let  $d = d_1^{\alpha_1} \dots d_m^{\alpha_m}$  be the full factorization of the polynomial  $d$ . Then for each  $i$  there is an  $l$  such that  $d_i^{\alpha_i}(k) \mid \text{den} \left( \frac{a_l(k+\rho-l)}{q(k+\rho-l)} \right)$ , so let

$$\nu_i = \min \left\{ l : d_i^{\alpha_i}(k) \mid \text{den} \left( \frac{a_l(k+\rho-l)}{q(k+\rho-l)} \right) \right\},$$

for  $i = 1, 2, \dots, m$ . Notice that any polynomial  $d_i^{\alpha_i}(k)$  divides the denominators of at least two coefficients of the right hand side of (19), since  $E^\rho \circ L^* \left( \frac{s}{q} \right) = 1 \in K[k]$ . This gives us  $0 \leq \nu_i \leq \rho - 1$ ,  $i = 1, 2, \dots, m$ . Since  $E^\rho \circ L^* \circ r = E^\rho \circ L^* \circ \frac{s}{q}$ , and  $s \perp q$ , we have

$$\nu_i = \min \{ l : d_i^{\alpha_i}(k) \mid \text{den}(a_l(k+\rho-l)r(k+\rho-l)) \}, \quad (20)$$

$i = 1, 2, \dots, m$ . Formula (7) is equivalent to

$$c_i(k + \rho - \tau) = \sum_{j=0}^{\tau} r(k + \rho - \tau + j) a_{\tau-j}(k + \rho - \tau + j) - 1$$

for  $0 \leq \tau \leq \rho - 1$ . If  $\tau = \nu_i$ , then it follows from this and from (20) that

$$d_i^{\alpha_i}(k) | \text{den}(r(k + \rho - \tau + j) a_{\tau-j}(k + \rho - \tau + j))$$

iff  $j = \tau$ . As a consequence we have

$$d_i^{\alpha_i}(k) | \text{den}(c_{\nu_i}(k + \rho - \nu_i)),$$

or, equivalently,

$$d_i^{\alpha_i}(k - \rho) | \text{den}(c_{\nu_i}(k - \nu_i)),$$

for  $i = 1, 2, \dots, m$ . This implies that

$$d_i^{\alpha_i}(k - \rho) | \text{den}(R),$$

for all  $i = 1, 2, \dots, m$ . Relation (18) follows since  $p(k) = d(k - \rho)$ .

From (16) it follows that  $\text{den}(R) | p$  as well. Since both  $p$  and  $\text{den}(R)$  are monic, we have  $p = \text{den}(R)$ .  $\square$

Now we can prove the following criterion for validity of the discrete Newton-Leibniz formula in the case where  $\mathcal{AS}$  succeeds on a given operator of order  $\rho \geq 1$ .

**Theorem 1** *Let*

- $L$  be of type (1), a sequence  $t(k)$  be defined and  $Lt = 0$  for all  $k$ ,
- $r = \frac{s}{q}$ ,  $s \perp q$ , satisfy (4), and  $R$  be found from (5),
- $p, \bar{L}$  be such as in (13), (14),
- $\bar{t}(k)$  be a sequence such that  $t(k) = p(k)\bar{t}(k)$  for all  $k$ .

*Then (3) is applicable everywhere iff  $\bar{L}\bar{t}(k) = 0$  for all  $k \in \mathbb{Z}$ . (If  $\bar{L}\bar{t}(k) = 0$  for all  $k \in \mathbb{Z}$ , then  $u = (R \circ p)\bar{t}$  in (3).)*

**Proof:** Let (3) be applicable everywhere with  $u = (R \circ p)\bar{t}$ . We have from (5):

$$E \circ R - R = 1 - rL, \tag{21}$$

and, as a consequence,

$$E \circ R \circ p - R \circ p - p = -rL \circ p. \quad (22)$$

By (15) we have

$$rL \circ p = rq\bar{L} = \frac{s}{q}q\bar{L} = s\bar{L},$$

therefore

$$E \circ R \circ p - R \circ p - p = -s\bar{L}. \quad (23)$$

Since the sequence  $\bar{t}$  is defined for all  $k \in \mathbb{Z}$ ,  $(E - 1)u = t$ ,  $u = (R \circ p)t$ , and  $t = p\bar{t}$  for all  $k \in \mathbb{Z}$ , we have

$$(E \circ R \circ p)\bar{t} - (R \circ p)\bar{t} - p\bar{t} = 0.$$

It follows from (23) that  $s\bar{L}\bar{t} = 0$ , and if  $k_0$  is such that  $s(k_0) \neq 0$  then  $\bar{L}\bar{t}(k_0) = 0$  (i.e., the value of the term  $\bar{L}\bar{t}$  is equal to 0 when  $k = k_0$ ). If  $s(k_0) = 0$ , then by  $s(k) \perp q(k)$  we have  $q(k_0) \neq 0$  and

$$\bar{L}\bar{t}(k_0) = \frac{1}{q(k_0)}Lp(k_0)\bar{t}(k_0) = \frac{1}{q(k_0)}Lt(k_0)$$

as a consequence of (15). However,  $Lt = 0$  identically, hence  $\bar{L}\bar{t}(k_0) = 0$ .

If  $\bar{L}\bar{t}(k) = 0$  for all  $k \in \mathbb{Z}$  then (3) is applicable everywhere with  $u = (R \circ p)\bar{t}$  by Theorem 5 of [4].  $\square$

**Example 2** In Example 6 from [4] the operator  $L = (k - 3)(k - 2)(k + 1)E^2 - (k - 3)(k^2 - 2k - 1)E - (k - 2)^2$  was considered to demonstrate some sufficient conditions of applicability of the discrete Newton-Leibniz formula. It was shown, in particular, that  $\mathcal{AS}$  succeeds on  $L$  and returns

$$r = \frac{-1}{(k - 2)(k - 3)}, \quad R = kE + \frac{1}{k - 3}.$$

Apply the criterion from Theorem 1 to  $L$ . We get  $q(k) = (k - 2)(k - 3)$ ,  $p = k - 3$ , and

$$\bar{L} = (k - 1)(k + 1)E^2 - (k^2 - 2k - 1)E - (k - 2).$$

We have  $\dim V(\bar{L}) = 2$ , since each of solutions of  $\bar{L}\bar{t} = 0$  is defined uniquely by  $\bar{t}(2)$  and  $\bar{t}(3)$  and by the equation  $\bar{L}\bar{t} = 0$  when  $k < 2$  or  $k > 3$ . The sequences  $p(k)\bar{t}_1(k)$ ,  $p(k)\bar{t}_2(k)$  such that  $\bar{t}_1(k), \bar{t}_2(k) \in V(\bar{L})$ ,  $\bar{t}_1(2) = 0$ ,



$\bar{t}_1(3) = 1, \bar{t}_2(2) = 1, \bar{t}_2(3) = 0$  are linearly independent over  $\mathbb{C}$ : while  $p(2)\bar{t}_1(2) = p(3)\bar{t}_1(3) = 0$ , nevertheless  $p(4)\bar{t}_1(4) = -\frac{1}{3}, p(4)\bar{t}_2(4) = 0$ , and

$$\begin{vmatrix} p(2)\bar{t}_1(2) & p(4)\bar{t}_1(4) \\ p(2)\bar{t}_2(2) & p(4)\bar{t}_2(4) \end{vmatrix} \neq 0.$$

By our criterion, formula (3) is applicable to  $t(k) \in V(L)$  iff  $t(k) = (k - 3)(c_1\bar{t}_1(k) + c_2\bar{t}_2(k))$ ,  $c_1, c_2 \in \mathbb{C}$ . Notice that  $\dim V(L) = 3$ : we can take any  $t(2), t(3), t(4), t(5)$  such that

$$(k - 3)(k - 2)(k + 1)t(k + 2) - (k - 3)(k^2 - 2k - 1)t(k + 1) - (k - 2)^2t(k) = 0$$

for  $k = 2, 3$  (this gives the only constraint  $t(3) = 0$ ) and define  $t(k)$  by the equation  $Lt = 0$  when  $k < 2$  or  $k > 5$ .

## 4 The case $\text{ord} L = 1$

In the case of  $\text{ord} L = 1$  it is possible to prove that  $\bar{L}$  and  $p$ , defined as in (13), (14), have some additional useful properties. This enables us to simplify the general criterion from Theorem 1.

**Proposition 2** *Let  $\rho = 1$  and  $\bar{L}$  be as in (14). If  $\bar{L} = \bar{a}_1(k)E + \bar{a}_0(k)$  then  $\bar{a}_1(k)|a_1(k), \bar{a}_0(k)|a_0(k)$ .*

**Proof:** It follows from (4) (the case  $\rho = 1$ ), i.e., from

$$a_0(k + 1)\frac{s(k + 1)}{q(k + 1)} + a_1(k)\frac{s(k)}{q(k)} = 1,$$

that the denominators of both terms (after reduction) in the left-hand side are equal:

$$\frac{q(k + 1)}{\gcd(a_0(k + 1), q(k + 1))} = \frac{q(k)}{\gcd(a_1(k), q(k))}. \quad (24)$$

We can compute  $p(k)$  using this. Indeed,

$$E \circ L^* \circ \frac{1}{q} = \frac{a_0(k + 1)}{q(k + 1)}E + \frac{a_1(k)}{q(k)}.$$

Therefore if  $d(k) \in K[k]$  and  $B \in K[k, E]$  are such that the coefficients of  $B$  are relatively prime and

$$E \circ L^* \circ \frac{1}{q} = \frac{1}{d}B$$

then

$$d(k) = \frac{q(k)}{\gcd(a_1(k), q(k))}$$

and

$$p(k) = d(k-1) = \frac{q(k-1)}{\gcd(a_1(k-1), q(k-1))}. \quad (25)$$

By (24), (25) we have

$$L \circ p = a_1(k) \left( \frac{q(k)}{\gcd(a_1(k), q(k))} \right) E + a_0(k) \left( \frac{q(k)}{\gcd(a_0(k), q(k))} \right).$$

The right hand side of this equation can be rewritten as

$$q(k) \left( \frac{a_1(k)}{\gcd(a_1(k), q(k))} E + \frac{a_0(k)}{\gcd(a_0(k), q(k))} \right).$$

Therefore

$$\bar{L} = \frac{a_1(k)}{\gcd(a_1(k), q(k))} E + \frac{a_0(k)}{\gcd(a_0(k), q(k))}. \quad (26)$$

□

**Corollary 1** *In the case of  $\text{ord} L = 1$  the coefficients of  $\bar{L}$  are relatively prime, and as a consequence, any  $K$ -valued sequence  $\bar{t}$  such that  $\bar{L}\bar{t} = 0$  is a hypergeometric term.*

By (10) the right-hand side of (25) is equal to the denominator of a rational solution  $r'(k)$  of equation (9). We have

**Corollary 2** *In the case of  $\text{ord} L = 1$  the polynomial  $p$  is the denominator of a rational solution of equation (9). When  $p$  is known,  $\bar{L}$  can be computed by removing from  $L \circ p$  the greatest common polynomial factor of its coefficients.*

If  $\text{ord} L = 1$  and one uses  $\mathcal{GA}$ , then Theorem 1 can be reformulated as the following criterion.

**Theorem 2** *Let  $L$  be of type (8), and let  $\frac{f}{p}$ ,  $f \perp p$ , be a rational solution of Gosper's equation (9). Then the discrete Newton-Leibniz formula is applicable everywhere to  $t$ , iff  $t = p\bar{t}$  for some hypergeometric term  $\bar{t}$  defined everywhere. If such  $\bar{t}$  exists, then  $u = f\bar{t}$  in (3).*

**Proof:** This follows from Theorem 1 and Corollary 1. □

**Example 3** (Example 1 continued.) We have  $t_2(k) = k\bar{t}_2(k)$ , where

$$\bar{t}_2(k) = \begin{cases} \frac{(-1)^k}{(-k-1)!}, & \text{if } k < 0, \\ 0, & \text{if } k \geq 0 \end{cases}$$

is a hypergeometric term defined everywhere. We take  $u(k) = \bar{t}_2(k)$  in (3).

For the sequence  $t_1(k)$  we have  $t_1(k) = k\bar{t}_1(k)$ , where

$$\bar{t}_1(k) = \begin{cases} 0, & \text{if } k < 0, \\ k!, & \text{if } k > 0. \end{cases}$$

The sequence  $\bar{t}_1$  is not a hypergeometric term for any value of  $\bar{t}_1(0)$ .

We can summarize Corollaries 1,2 and Theorem 2 as follows:

**Corollary 3** If  $L$  is of type (8),  $\mathcal{GA}$  succeeds on  $L$  and returns  $R \in K(k)$ ,  $\text{den}(R) = p$ , then

$$V_R(L) = p \cdot V(\text{pp}(L \circ p)),$$

where the operator  $\text{pp}(L \circ p)$  is computed by removing from  $L \circ p$  the greatest common polynomial factor of its coefficients.

## 5 Indefinite summable hypergeometric terms which are definite summable by the discrete Newton-Leibniz formula

If an operator  $L$  of the form (8) is such that  $\mathcal{AS}$  or  $\mathcal{GA}$  succeeds on  $L$ , then, using Theorem 1, we can describe the space  $V_R(L)$ : this is the space of sequences of the form  $p\bar{t}$ ,  $\bar{L}\bar{t} = 0$ .

**Proposition 3** Let  $p, \bar{L}$  be as in (25), (26). Then there exists a sequence  $\bar{t}$  which is defined everywhere and is such that  $\bar{L}\bar{t} = 0$  for all  $k \in \mathbb{Z}$ , and that  $p\bar{t}$  is a non-zero sequence.

**Proof:** By (24), (25) we can write  $p(k) = q(k)/\text{gcd}(a_0(k), q(k))$ . So by (26),  $p$  is relatively prime with both  $\bar{a}_1(k-1)$  and  $\bar{a}_0(k)$ .

If the equation  $\bar{a}_1(k-1) = 0$  has integer roots then set  $k'$  to be the maximal one. There exists a sequence  $\bar{t}$  which is defined everywhere and satisfies  $\bar{L}\bar{t} = 0$  for all  $k$ , such that  $\bar{t}(k') = 1$  (and  $\bar{t}(k) = 0$  for all  $k < k'$ ). Then  $p\bar{t}$  is not zero at  $k'$  because  $p$  is relatively prime with  $\bar{a}_1(k-1)$ . If

the equation  $\bar{a}_0(k) = 0$  has integer roots then set  $k''$  to be the minimal one. There exists a sequence  $\bar{t}$  which is defined everywhere and satisfies  $\bar{L}\bar{t} = 0$  for all  $k$ , such that  $\bar{t}(k'') = 1$  (and  $\bar{t}(k) = 0$  for all  $k > k''$ ). Then  $p\bar{t}$  is not zero at  $k''$  because  $p$  is relatively prime with  $\bar{a}_0(k)$ . If  $\bar{a}_1(k-1)\bar{a}_0(k) \neq 0$  for all integer  $k$ , then there exists a sequence  $\bar{t}$  which is defined everywhere, and satisfies  $\bar{L}\bar{t} = 0$  and  $\bar{t}(k) \neq 0$  for all  $k$ . It is evident that  $p\bar{t}$  is a non-zero sequence.  $\square$

As a consequence we get the following theorem.

**Theorem 3** *Let  $\mathcal{GA}$  succeed on an operator  $L$  of type (8), and let  $r'(k) = \frac{L}{p}$ ,  $f \perp p$ , be a rational solution of Gosper's equation (9). Then there exists a hypergeometric term  $\bar{t}$  which is defined everywhere, and is such that the hypergeometric term  $t = p\bar{t}$  is not zero, satisfies  $Lt = 0$ , and formula (3) is valid with  $u = f\bar{t}$  for all  $v \leq w$ .*

It is possible to give examples showing that in some cases  $\text{ord} L = 1$ ,  $\dim V_R(L) > 1$ .

**Example 4** *Let  $L = 2(k^2 - 4)(k - 9)E - (2k - 3)(k - 1)(k - 8)$ . Then  $\mathcal{GA}$  succeeds on  $L$  and returns*

$$r'(k) = -\frac{2(k-3)(k+1)}{k-9}.$$

Here  $p(k) = k - 9$  and  $\bar{L} = 2(k^2 - 4)E - (2k - 3)(k - 1)$ . Any sequence  $\bar{t}$  which satisfies the equation  $\bar{L}\bar{t} = 0$  has  $\bar{t}(k) = 0$  for  $k = 2$  or  $k \leq -2$ . The values of  $\bar{t}(1)$  and  $\bar{t}(3)$  can be chosen arbitrarily, and all the other values are determined uniquely by the recurrence  $2(k^2 - 4)\bar{t}(k+1) = (2k - 3)(k - 1)\bar{t}(k)$ . Hence the solution space of  $\bar{L}\bar{t} = 0$  has dimension 2; the space of sequences  $p\bar{t}$ ,  $\bar{L}\bar{t} = 0$ , has dimension 2 too, since  $p(1), p(3) \neq 0$ .

At the same time, the space  $V(L)$  of all solutions of  $Lt = 0$  is of dimension 3. Indeed, if  $Lt = 0$ , then  $t(-2) = t(2) = t(9) = 0$ . The value  $t(k) = 0$  from  $k = -2$  propagates to all  $k \leq -2$ , but on each of the integer intervals  $[-1, 0, 1]$ ,  $[3, 4, 5, 6, 7, 8]$  and  $[10, 11, \dots]$  we can choose one value arbitrarily, and the remaining values on that interval are then determined uniquely. A sequence  $t \in V(L)$  belongs to  $V_R(L)$  iff  $22t(10) - 13t(8) = 0$ .

Set

$$m = \min(\{\infty\} \cup \{n \in \mathbb{Z} : a_0(n) = 0\}), \quad (27)$$

$$M = \max(\{-\infty\} \cup \{n \in \mathbb{Z} : a_1(n-1) = 0\}). \quad (28)$$

If  $M < m$ , then pick any integer  $l$  such that  $M \leq l \leq m$  and then reset  $M = m = l$ . It is clear that any sequence  $t \in V(L)$  is uniquely determined by the vector  $(t(m), t(m+1), \dots, t(M))$ , whose entries satisfy the system of algebraic linear equations:

$$a_1(m+i)t(m+i+1) + a_0(m+i)t(m+i) = 0, \quad i = 0, \dots, M-m-1 \quad (29)$$

(if  $m = M$  then  $t(m)$  can be chosen arbitrarily).

Using the values  $m, M$  we can present a more formal description of our algorithm for constructing a basis of  $V_R(L)$ , where  $L$  of type (8) is such that  $\mathcal{GA}$  succeeds on  $L$  and returns  $R$ . The algorithm starts with computing  $m, M$  as above, and  $\bar{L} = \bar{a}_1(k) + \bar{a}_0(k)$ ,  $p(k)$  as in Corollaries 2, 3. Then the system of algebraic linear equations with the unknowns  $z_m, z_{m+1}, \dots, z_M$ :

$$\bar{a}_1(m+i)z_{m+i+1} + \bar{a}_0(m+i)z_{m+i} = 0, \quad i = 0, \dots, M-m-1 \quad (30)$$

has to be solved. (Notice that if the vector  $(z_m, z_{m+1}, \dots, z_M)$  satisfies (30), then the vector  $(t(m), t(m+1), \dots, t(M))$ , such that  $t(m+i) = p(m+i)z_{m+i}$ ,  $i = 0, \dots, M-m-1$ , satisfies (29).) Let the dimension of the solution space of (30) be  $\lambda$ ,

$$(z_{1,m}, \dots, z_{1,M}), \quad \dots, \quad (z_{\lambda,m}, \dots, z_{\lambda,M})$$

be a basis of this space, and the space generated by the vectors

$$(p(m)z_{1,m}, \dots, p(M)z_{1,M}), \quad \dots, \quad (p(m)z_{\lambda,m}, \dots, p(M)z_{\lambda,M})$$

be of dimension  $\mu \leq \lambda$  (if  $p$  has no root among the numbers  $m, m+1, \dots, M$ , then  $\mu = \lambda$ ). W.l.g. we can assume that the vectors

$$(p(m)z_{1,m}, \dots, p(M)z_{1,M}), \quad \dots, \quad (p(m)z_{\mu,m}, \dots, p(M)z_{\mu,M})$$

are linearly independent. Then we get a basis  $p\bar{t}_1, \dots, p\bar{t}_\mu$  of  $V_R(L)$ , where the sequence  $\bar{t}_i$  is defined by

$$\bar{t}_i(m) = z_{i,m}, \quad \bar{t}_i(m+1) = z_{i,m+1}, \quad \dots, \quad \bar{t}_i(M) = z_{i,M},$$

and by the equation  $\bar{L}\bar{t} = 0$  when  $k < m$  or  $k > M$ .

We finish with the following remark. If we are interested in the applicability of (3) only for the case  $k \geq k_0$ , where  $k_0$  is a given integer, then we change (27), 28 by

$$m = \min(\{\infty\} \cup \{n \in \mathbb{Z}, n \geq k_0 : a_0(n) = 0\}),$$

$$M = \max(\{k_0\} \cup \{n \in \mathbb{Z} : a_1(n-1) = 0\}).$$

If  $M < m$ , then reset  $m = M$ . Respectively, if we are interested only in the case  $k \leq k_0$ , then

$$m = \min(\{k_0\} \cup \{n \in \mathbb{Z} : a_0(n) = 0\}),$$

$$M = \max(\{-\infty\} \cup \{n \in \mathbb{Z}, n \leq k_0 : a_1(n-1) = 0\}),$$

and if  $M < m$ , then reset  $M = m$ .

If in Examples 1, 3 we are interested only in the case  $k \geq 0$ , then we get, e.g., that (3) is applicable to  $t_1(k)$  when  $w \geq v \geq k_0 = 0$  with  $u(k) = k!$ .

## References

- [1] S. A. Abramov, Rational solutions of linear difference and differential equations with polynomial coefficients, *USSR Comput. Math. Phys.* **29** (1989), 7–12. Transl. from *Zh. vychisl. mat. mat. fiz.* **29** (1989), 1611–1620.
- [2] S. A. Abramov, Rational solutions of linear difference and  $q$ -difference equations with polynomial coefficients, *Programming and Comput. Software* **21** (1995), 273–278. Transl. from *Programmirovaniye* **21** (1995), 3–11.
- [3] S. A. Abramov, M. van Hoeij, Integration of solutions of linear functional equations, *Integral transforms and Special Functions* **8** (1999), 3–12.
- [4] S. A. Abramov and M. Petkovšek, Gosper's Algorithm, Accurate Summation, and the discrete Newton-Leibniz formula, *Proc. ISSAC'05*, ACM Press (2005), 5–12.
- [5] R. W. Gosper, Jr., Decision procedure for indefinite hypergeometric summation, *Proc. Natl. Acad. Sci. USA* **75** (1978), 40–42.